Hooke's Rule and Simple Harmonic Motion(SHM)

Pre-Lecture Questions

Problem Set #34 (due next time)

Lecture Outline

- I. A Mass at the End of a Spring
- 2. The SHM Equations of Motion

Pre-Class Summary:

The force exerted by a spring is given by Hooke's Rule $\vec{F}_s = -k\vec{x}$. Then the Second Law gives an acceleration of $a = -\frac{k}{m}x$ resulting in the

Equations of Motion for SHM:

$$a(x) = -\omega^{2}x$$

$$x(t) = A\cos(\omega t + \delta)$$

$$v(t) = -\omega A\sin(\omega t + \delta)$$

$$v(x) = \pm \omega \sqrt{A^{2} - x^{2}}$$

$$a(t) = -\omega^{2}A\cos(\omega t + \delta)$$

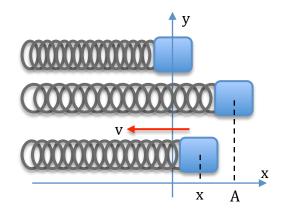
where A is the amplitude of the motion, ω is the angular frequency, and δ is the phase angle.

All of these equations follow from the first one. So any time we have a system where the acceleration is equal to the negative of a constant times the position, we will get this SHM and the angular frequency will be equal to the root of the constant.

For a mass on the end of a spring, $\omega = \sqrt{\frac{k}{m}}$.

Example 1: A 300g mass on the end of a spring oscillates at 1.50Hz. Find (a)the angular frequency and (b)the spring constant.

In the upper image a mass, m, rests at the end of a spring of spring constant, k. In the middle image, the mass has been moved to the right a distance A. In the bottom image, the mass has been released and it is now at the position x with a speed v.



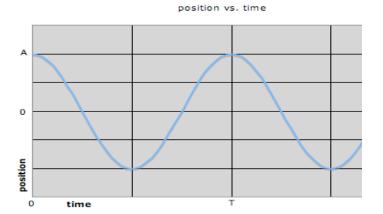
- 1. Draw the horizontal forces that act on the mass in the bottom image. Ignore friction.
- 2. Apply the Second Law and solve for the acceleration in terms of m, k, x, and A.

3. Sketch a graph of the position of the mass versus time. Indicate A in the graph.

4. The curve could be described mathematically as,

$$x = A\cos\theta$$

where x represents the (position) (time) and θ is related to the (position) (time).



5. In general, the maximum value of the cosine function is _____. The maximum value of x is called the _____. So the A must represent the _____.

6. If the $\cos \theta$ must be one at t = 0s, then the value of $\cos \theta$ must be _____ after one period. If θ is zero at t = 0s, then θ must be equal to _____ after one period.

- 7. For any angle θ at any time t, complete the following ratio, $\frac{\theta}{2\pi} = \frac{\Box}{T}$.
- 8. Solve this equation for θ then rewrite $x = A\cos\theta$ in terms of t:

Rewriting $x = A\cos 2\pi \frac{t}{T}$ in terms of $\omega = \frac{2\pi}{T}$ gives the position as a function of time for the mass,

$$x = A \cos \omega t$$

9. Find the velocity as a function of time for the mass at the end of a spring,

10. Find the acceleration as a function of time for the mass at the end of a spring,

- II. Substitute the equation for the position, $x = A\cos\omega t$, into the acceleration to get the acceleration as a function of position,
- 12. Compare the result of 11 to the result of part 2 to get the angular frequency for the mass on the end of a spring.

Equations of Motion for SHM:

$$a(x) = -\omega^{2}x$$

$$x(t) = A\cos(\omega t + \delta)$$

$$v(t) = -\omega A\sin(\omega t + \delta)$$

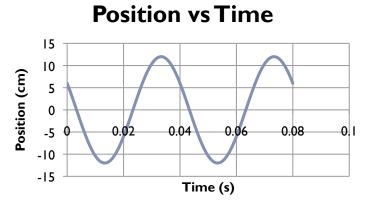
$$v(x) = \pm \omega \sqrt{A^{2} - x^{2}}$$

$$a(t) = -\omega^{2}A\cos(\omega t + \delta)$$

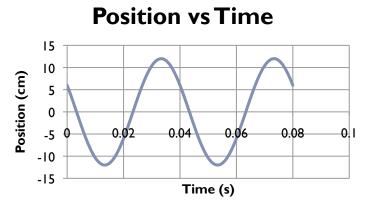
where A is the amplitude of the motion, ω is the angular frequency, and δ is the phase angle.

For a mass on the end of a spring, $\omega = \sqrt{\frac{k}{m}}$.

Example 2: From the graph at the right find (a)the amplitude, (b)the period, (c)the frequency, and (d)the angular frequency that describe the motion.



Example 3: From the graph at the right find (a)the phase angle, (b)the position as a function of time, (c)the velocity as a function of time, and (d)the acceleration as a function of time.



Lecture 34 - Summary

The force exerted by a spring is given by Hooke's Rule $\vec{F}_s = -k\vec{x}$. Then the Second Law gives an acceleration of $a = -\frac{k}{m}x$ resulting in the

Equations of Motion for SHM:

$$a(x) = -\omega^{2}x$$

$$x(t) = A\cos(\omega t + \delta)$$

$$v(t) = -\omega A\sin(\omega t + \delta)$$

$$v(x) = \pm \omega \sqrt{A^{2} - x^{2}}$$

$$a(t) = -\omega^{2}A\cos(\omega t + \delta)$$

where A is the amplitude of the motion, ω is the angular frequency, and δ is the phase angle.

All of these equations follow from the first one. So any time we have a system where the acceleration is equal to the negative of a constant times the position, we will get this SHM and the angular frequency will be equal to the root of the constant.

For a mass on the end of a spring, $\omega = \sqrt{\frac{k}{m}}$.